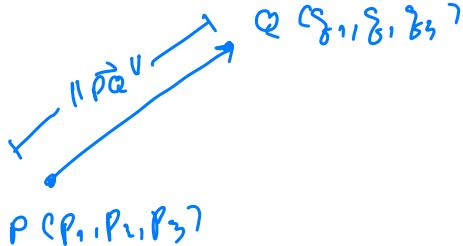
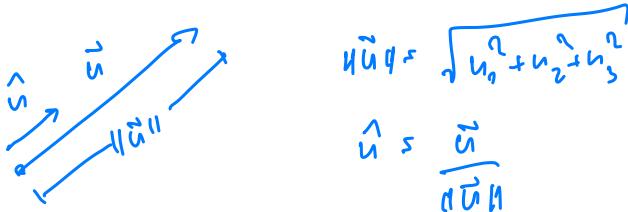


ກວດສອບ: ໂດຍມີມູນຄົງໃຫຍ່



$$\begin{aligned}\vec{PQ} &= \vec{Q} - \vec{P} \\ &= \begin{pmatrix} q_1 \\ q_2 \\ q_3 \end{pmatrix} - \begin{pmatrix} p_1 \\ p_2 \\ p_3 \end{pmatrix} = \begin{pmatrix} q_1 - p_1 \\ q_2 - p_2 \\ q_3 - p_3 \end{pmatrix}\end{aligned}$$



$$\begin{aligned}\|\vec{u}\| &= \sqrt{u_1^2 + u_2^2 + u_3^2} \\ \hat{n} &= \frac{\vec{u}}{\|\vec{u}\|}\end{aligned}$$

- ຕົວທີ່ໄປລະບົບການຈຳນວນ (dot product / cross product.)

⇒ Dot product (ເຈັບຜິດສົນນະພົບ)

$$\text{ຈົດ } \vec{u} = (u_1, u_2, u_3), \quad \vec{v} = (v_1, v_2, v_3)$$

$$\vec{u} \cdot \vec{v} = u_1 v_1 + u_2 v_2 + u_3 v_3$$

scalar.

vectors

Ex: ກົດ ວິທີ ອະນຸຍາກ (ທີ່) ຂາດຕະກົດ.

$$1.) \underbrace{(-1, 7, 4)}_{\vec{u}} \cdot \underbrace{(6, 2, -\frac{1}{2})}_{\vec{v}} = (-1 \cdot 6 + 7 \cdot 2 + 4 \cdot -\frac{1}{2}) = -6 + 14 - 2 = 6$$

$$2.) \text{ຈົດ } \vec{u} = \vec{i} + 2\vec{j} - 3\vec{k}, \quad \vec{v} = 2\vec{j} - \vec{k} \Rightarrow \vec{u} \cdot \vec{v} (+\vec{0})$$

$$\text{ज्ञानिका } \vec{u} = (1, 2, -3), \vec{v} = (0, 2, -1)$$

$$\vec{u} \cdot \vec{v} = 1 \cdot 0 + 2 \cdot 2 + (-3)(-1) = 0 + 4 + 3 = 7 \quad \blacksquare$$

समझने का दृष्टिकोण: यदि $\vec{u}, \vec{v}, \vec{w}$ इनका ग्राहक, तो निम्नलिखित विधियाँ लागती हैं।

$$1.) \vec{u} \cdot \vec{u} = \|\vec{u}\|^2 \Rightarrow \vec{u} \cdot \vec{u} = u_1^2 + u_2^2 + u_3^2 = \|\vec{u}\|^2$$

$$2.) \vec{u} \cdot \vec{v} = \vec{v} \cdot \vec{u} \Rightarrow \vec{u} \cdot \vec{v} = u_1 v_1 + u_2 v_2 + u_3 v_3 \\ = u_1 u_1 + u_2 u_2 + u_3 u_3 = \vec{v} \cdot \vec{u}$$

$$3.) \vec{u} \cdot (\vec{v} \pm \vec{w}) = \vec{u} \cdot \vec{v} \pm \vec{u} \cdot \vec{w}$$

$$\Rightarrow \vec{u} \cdot (\vec{v} \pm \vec{w}) = \vec{u} \cdot (v_1 \pm w_1, v_2 \pm w_2, v_3 \pm w_3)$$

$$= u_1(v_1 \pm w_1) + u_2(v_2 \pm w_2) + u_3(v_3 \pm w_3)$$

$$= (u_1 v_1 \pm u_1 w_1) + (u_2 v_2 \pm u_2 w_2) + (u_3 v_3 \pm u_3 w_3)$$

$$= (u_1 v_1 + u_2 v_2 + u_3 v_3) \pm (u_1 w_1 + u_2 w_2 + u_3 w_3) \\ = \vec{u} \cdot \vec{v} \pm \vec{u} \cdot \vec{w}. \quad \blacksquare$$

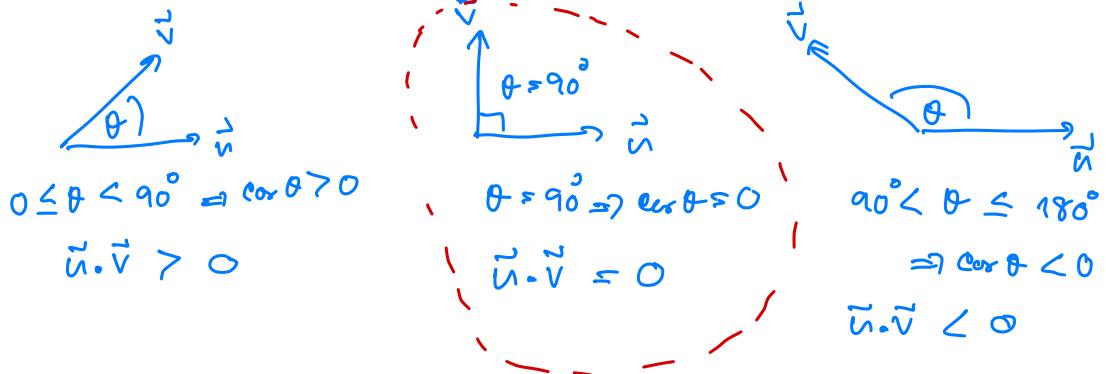
$$4.) (k\vec{u}) \cdot \vec{v} = \vec{u} \cdot (k\vec{v})$$

$$5.) \vec{0} \cdot \vec{u} = 0$$

मानविकी:

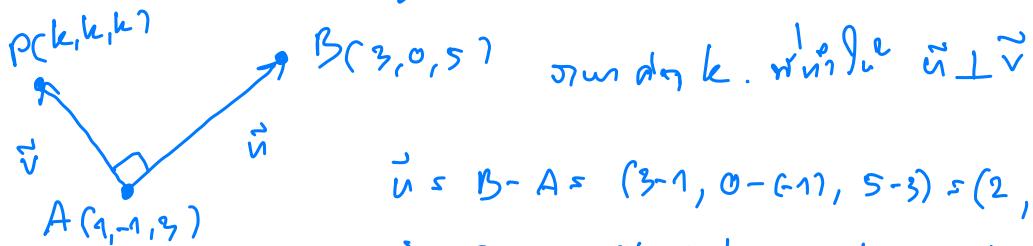
$$\boxed{\vec{u} \cdot \vec{v} = \|\vec{u}\| \|\vec{v}\| \cos \theta}$$

परिणाम: $\vec{u} \cdot \vec{v}$ अद्वयात्मक (\pm) विकल्पों के बीच $\cos \theta$.



Ex: 找出 k 使得平行四边形的顶点 A(1, -1, 3) 与 B(3, 0, 5)

平行四边形的顶点 P(k, k, k)



$$\vec{u} \perp \vec{v} \text{ 使得 } \vec{u} \cdot \vec{v} = 0$$

$$0 = \vec{u} \cdot \vec{v} = 2 \cdot (k-1) + 1 \cdot (k+1) + 2 \cdot (k-3)$$

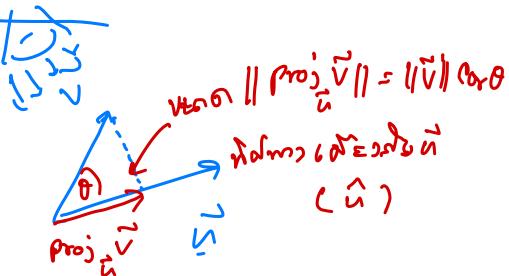
$$\Rightarrow 0 = 2k-2 + k+1 + 2k-6 = 5k-7$$

$$\Rightarrow 5k = 7 \Rightarrow k = \frac{7}{5} \quad \therefore P = \left(\frac{7}{5}, \frac{7}{5}, \frac{7}{5}\right)$$

⇒ projection of vector.

$$\boxed{\text{proj}_{\vec{u}} \vec{v} = (\|\vec{v}\| \cos \theta) \hat{u}}$$

← vectors → norms



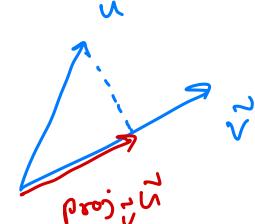
$$\begin{aligned}
 &= \|\tilde{v}\| \cos \theta \frac{\hat{u}}{\|\hat{u}\|} \cdot \frac{\|\tilde{u}\|}{\|\tilde{u}\|} \\
 &= \underbrace{\|\tilde{u}\| \|\tilde{v}\| \cos \theta}_{\tilde{u} \cdot \tilde{v}} \frac{\hat{u}}{\|\hat{u}\|^2} \\
 \Rightarrow \text{proj}_{\hat{u}} \tilde{v} &= \boxed{\frac{\hat{u} \cdot \tilde{v}}{\|\hat{u}\|^2} \cdot \hat{u}}
 \end{aligned}$$

proj _{\hat{u}} \tilde{v} = $\underbrace{\|\hat{u}\| \|\tilde{v}\| \cos \theta}_{\tilde{u} \cdot \tilde{v}}$
 proj _{\hat{u}} \tilde{v} = $(\tilde{v} \cdot \hat{u}) \hat{u}$

Ex: $\tilde{u} = 6\hat{i} + 3\hat{j} + 2\hat{k}$, $\tilde{v} = \hat{i} - 2\hat{j} - 2\hat{k}$

then. $\text{proj}_{\tilde{v}} \tilde{u}$

$$\text{proj}_{\tilde{v}} \tilde{u} = (\tilde{u} \cdot \hat{v}) \hat{v} \quad \left(\text{so } \hat{v} = \frac{\tilde{v}}{\|\tilde{v}\|} \right)$$



$$\text{on } \hat{v} = \frac{1}{\|\tilde{v}\|} (1, -2, -2) = \frac{1}{\sqrt{1^2 + (-2)^2 + (-2)^2}} (1, -2, -2) = \frac{1}{3} (1, -2, -2)$$

$$\text{So, } \text{proj}_{\tilde{v}} \tilde{u} = (\tilde{u} \cdot \hat{v}) \hat{v} = \left[(6, 3, 2) \cdot \frac{1}{3} (1, -2, -2) \right] \frac{1}{3} (1, -2, -2)$$

$$= \frac{1}{9} [6 \cdot 1 + 3 \cdot (-2) + 2 \cdot (-2)] (1, -2, -2)$$

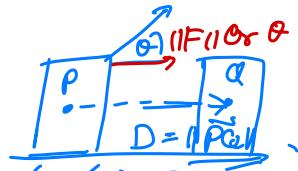
$$= -\frac{4}{9} (1, -2, -2)$$

⊗ F

মুক্তি পাওয়ার দিয়ে কোণ ও উ

$$\omega = \underbrace{\|F\| \cos \theta}_{\text{ডায়াগ্রাম}} \cdot D$$

ডায়াগ্রাম.



$$\Rightarrow \omega = \|\vec{F}\| \cos \theta \cdot \|\vec{PQ}\| = \|\vec{F}\| \|\vec{PQ}\| \cos \theta = \vec{F} \cdot \vec{PQ}$$

2.16 $\omega = \vec{F} \cdot \vec{PQ}$

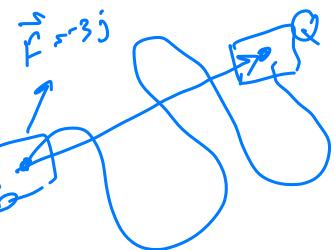
ສະບັບທີ່ກຳນົດ \vec{PQ} .
ມີຄວາມ
ມີຄວາມ

Ex. ທາງຈິຕຸກໂລດອັນ $\vec{F} = -3\hat{j}$ N. ມີກຳນົດໃຫຍ່
ທາງ $(1, 3) \xrightarrow{\text{ກຳນົດ}} (4, 7)$

$$\omega = \vec{F} \cdot \text{ກຳນົດ}, \quad \vec{PQ} = \begin{pmatrix} 4-1 \\ 7-3 \end{pmatrix}$$

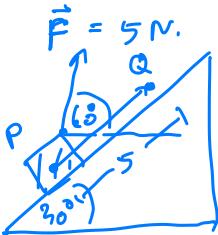
$$= (0, -3) \cdot (3, 4)$$

$$= \begin{pmatrix} 3 \\ 4 \end{pmatrix}$$



$$= 0 \cdot 3 + (-3) \cdot 4 = -12 \text{ N.m (J.)}$$

Ex:-



ທາງຈິຕຸກໂລດອັນ ດີວ່າມີຄວາມ

ກຳນົດຂອງ 5 m. ພົບ ຢູ່ລົດ.

$$\omega = \vec{F} \cdot \vec{PQ} = \|\vec{F}\| \|\vec{PQ}\| \cos \theta$$

$$= 5 \cdot 5 \cos(30^\circ) = 25 \cos(30^\circ)$$

- ວຽກຄູ່ຂອງສາມາດ (Cross product)

$$\vec{u} = (u_1, u_2, u_3), \quad \vec{v} = (v_1, v_2, v_3)$$

$$\vec{u} \times \vec{v} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix} = (u_2 v_3 - u_3 v_2) \vec{i} + (u_3 v_1 - u_1 v_3) \vec{j} + (u_1 v_2 - u_2 v_1) \vec{k}$$

Ex: If $\vec{u} = (1, 3, 4)$, $\vec{v} = (2, 7, -5)$ then $\vec{u} \times \vec{v}$

$$\begin{aligned}\vec{u} \times \vec{v} &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 3 & 4 \\ 2 & 7 & -5 \end{vmatrix} = (3 \cdot (-5) - 7 \cdot 4) \vec{i} + (4 \cdot 2 - (-5) \cdot 1) \vec{j} \\ &\quad + (1 \cdot 7 - 3 \cdot 2) \vec{k} \\ &= (-15 - 28) \vec{i} + (8 + 5) \vec{j} + (7 - 6) \vec{k} \\ &= -43 \vec{i} + 13 \vec{j} + \vec{k} = (-43, 13, 1)\end{aligned}$$

Lemma: $\vec{u} \times \vec{u} = \vec{0}$

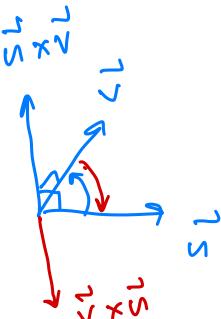
Proof: Because $\vec{u} \times \vec{v}$ is perpendicular to \vec{u} it is $\vec{0}$

$$\vec{u} \times \vec{v} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix} = (u_2 v_3 - u_3 v_2) \vec{i} + (u_3 v_1 - u_1 v_3) \vec{j} + (u_1 v_2 - u_2 v_1) \vec{k}$$

Now $\vec{u} \cdot (\vec{u} \times \vec{v}) = u_1(u_2 v_3 - u_3 v_2) + u_2(u_3 v_1 - u_1 v_3)$

$$(u_1, u_2, u_3) + u_3(u_1 v_2 - u_2 v_1)$$

$$\begin{aligned}&= (u_1 u_2 v_3 - u_1 u_3 v_2) + (u_2 u_3 v_1 - u_2 u_1 v_3) \\ &\quad + (u_3 u_1 v_2 - u_3 u_2 v_1) \\ &= 0.\end{aligned}$$



Lemma: $\vec{u} \times \vec{v} = -\vec{v} \times \vec{u}$

$$\underline{\text{សេចក្តី}}: \quad 1.) \quad \vec{u} \times \vec{v} = -(\vec{v} \times \vec{u})$$

$$2.) \quad (k\vec{u}) \times \vec{v} = k(\vec{u} \times \vec{v}) = \vec{u} \times (k\vec{v})$$

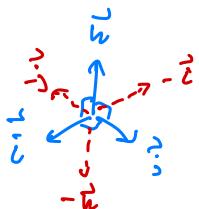
$$3.) \quad \vec{u} \times (\vec{v} + \vec{w}) = (\vec{u} \times \vec{v}) + (\vec{u} \times \vec{w})$$

$$4.) \quad (\vec{u} + \vec{v}) \times \vec{w} = (\vec{u} \times \vec{w}) + (\vec{v} \times \vec{w})$$

$$5.) \quad \vec{u} \cdot (\vec{v} \times \vec{w}) = (\vec{u} \times \vec{v}) \cdot \vec{w}$$

$$6.) \quad \vec{u} \times (\vec{v} \times \vec{w}) = (\vec{u} \cdot \vec{w})\vec{v} - (\vec{u} \cdot \vec{v})\vec{w}$$

វិប័ណ្ណ: លាកសមិទ្ធភាព និង សម្រាប់ គុណភាព និង សម្រាប់ គុណភាព.



$$\begin{aligned}\vec{i} \times \vec{j} &= \vec{k} = (-\vec{j}) \times \vec{i} \\ \vec{j} \times \vec{k} &= \vec{i} = (-\vec{i}) \times \vec{j} \\ \vec{k} \times \vec{i} &= \vec{j} = (-\vec{j}) \times \vec{k}\end{aligned}$$

លក្ខណៈ: \vec{u}, \vec{v} ជាលាកសមិទ្ធភាព និង សម្រាប់ គុណភាព $0 \leq \theta \leq \pi$ តាមដែរ

$$\boxed{\|\vec{u} \times \vec{v}\| = \|\vec{u}\| \|\vec{v}\| \sin \theta.}$$

