

## Wave equation

$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2}, \quad 0 < x < \ell, \quad t > 0 \quad (1a)$$

$$u(0, t) = u(\ell, t) = 0, \quad t > 0 \quad (1b)$$

$$u(x, 0) = f(x), \quad u_t(x, 0) = g(x), \quad 0 \leq x \leq \ell. \quad (1c)$$

**d'Alembert Representation** If we assume  $x \in (-\infty, \infty)$ ,

then we can show that

$$u(x, t) = F(x + ct) + G(x - ct),$$

is a solution to (1a) for any  $F$  and  $G$  that are twice differentiable.

To satisfy the initial condition (1c), the solution  $u$  takes the form

$$u(x, t) = \frac{1}{2}f(x - ct) + \frac{1}{2}f(x + ct) + \frac{1}{2c} \int_{x-ct}^{x+ct} g(z) dz.$$

*Example* Consider the problem with  $g = 0$  and  $f$  is given by

$$f(x) = \begin{cases} 1 & \text{if } -1 \leq x \leq 1, \\ 0 & \text{otherwise.} \end{cases}$$

In this case, the solution at time  $t$  looks like:

**Domain of dependence** The solution of the wave equation at  $(x, t)$  depends on the initial value at.....

**Explicit method** We approximate the second derivatives in (1a)

with the centered differences (in time and space) to get

$$\frac{u_{j,k+1} - 2u_{j,k} + u_{j,k-1}}{(\Delta t)^2} = c^2 \frac{u_{j+1,k} - 2u_{j,k} + u_{j-1,k}}{h^2}$$

we get the scheme

$$u_{j,k+1} = \lambda^2 u_{j+1,k} + 2(1 - \lambda^2) u_{j,k} + \lambda^2 u_{j-1,k} - u_{j,k-1}, \quad (2)$$

for  $j = 1, \dots, N$  and  $k = 1, \dots, M - 1$ . Here,  $\lambda = \frac{c\Delta t}{h}$ .

**Note** We still need to approximate  $u_{j,1}$  for  $j = 1, \dots, N$ .

**CFL condition** We can show that the CFL condition for the scheme (2) is  $\lambda \leq 1$ .

**Stability** We claim without proving that the stability condition for the scheme (2) is  $\lambda \leq 1$ .

## Laplace's equation

$$\nabla^2 u = 0, \quad (x, y) \in D, \quad (3a)$$

$$u = g(x, y), \quad (x, y) \in \partial D, \quad (3b)$$

where  $\nabla$  denotes  $(\frac{\partial}{\partial x}, \frac{\partial}{\partial y})$ .

**Maximum and Minimum principles** The maximum and minimum of the solution occurs on the boundary. It follows that the solution is unique and the problem is stable.

**Finite difference approximation** For a rectangular domain

$D \cup \partial D = [0, a] \times [0, b]$ , we discretize  $x$  and  $y$  into

$$x_j = j\Delta x, \quad j = 0, \dots, N + 1,$$

$$y_k = k\Delta y, \quad k = 0, \dots, M + 1,$$

where  $\Delta x = a/(N + 1)$  and  $\Delta y = b/(M + 1)$ .

As before, we approximate the second derivatives in (3a) with the centered differences to get

$$\frac{u_{j+1,k} - 2u_{j,k} + u_{j-1,k}}{(\Delta x)^2} + \frac{u_{j,k+1} - 2u_{j,k} + u_{j,k-1}}{(\Delta y)^2} = 0.$$

Let  $\lambda = \frac{\Delta y}{\Delta x}$ , we get the scheme

$$-\lambda^2 u_{j+1,k} + 2(1 + \lambda^2)u_{j,k} - \lambda^2 u_{j-1,k} - u_{j,k-1} - u_{j,k+1}, \quad (4)$$

for  $j = 1, \dots, N$  and  $k = 1, \dots, M$ . Here,  $\lambda = \frac{\Delta y}{\Delta x}$ .

The boundary condition (3b) gives the values for the points on the boundary:  $u_{0,k}$ ,  $u_{N+1,k}$ ,  $u_{j,0}$ , and  $u_{j,M+1}$ .

*Vector form* Let  $N = M = 3$ , and let  $g$  be defined such that  $g := g_L, g_R, g_T, g_B$  on the left, right, top, and bottom of  $\partial D$  respectively. We can then write the scheme (4) in vector-matrix form as: